

27th IFIP TC7 Conference 2015 on System Modelling and Optimization

Wellposedness, control, and observability theories for partial differential equations

Variational Formulation for Euler Equation in Moving Domain

Jean-Paul Zolésio

CNRS-INLN
Sophia Antipolis, France

Jean-Paul.Zolesio@inria.fr

Abstract: We extend some variational principle for Euler incompressible flow* to viscous model.

*Shape-Morphic Metrics. In M. Ruzhansky and J. Wirth, editors, *Modern aspects of the theory of partial differential equations*, volume 216 of *Operator Theory: Advances and Applications*, pages 167–189, Birkhäuser, 2011.